

# R-1000iA/80H



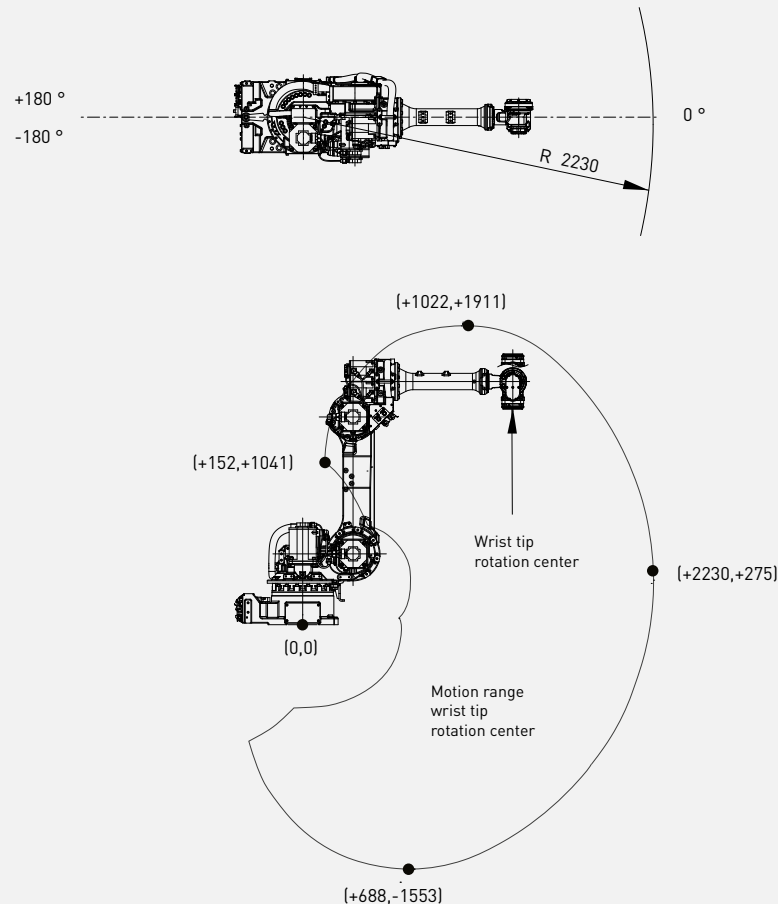
Max. load capacity  
at wrist: **80 kg**



Max. reach:  
**2230 mm**

Controlled axes	Repeatability (mm)	Mechanical weight (kg)	Motion range (°)						Maximum speed (°/s)						J4 Moment/ Inertia (Nm/kgm <sup>2</sup> )	J5 Moment/ Inertia (Nm/kgm <sup>2</sup> )	J6 Moment/ Inertia (Nm/kgm <sup>2</sup> )
			J1	J2	J3	J4	J5	J6	J1	J2	J3	J4	J5	J6			
5	± 0.03*	610	360	245	215	20	720	-	185	180	180	180	500	-	-/48	-/25	-

## Working range



### Robot

	R-1000iA/80H
Robot footprint [mm]	1540 X 1480
Mounting position Floor	●
Mounting position Upside down	●
Mounting position Angle	-



### Controller

	R30iB Plus
Open air cabinet	-
Mate cabinet	○
A-cabinet	●
B-cabinet	○
iPendant Touch	●

### Electrical connections

Voltage 50/60Hz 3phase [V]	380-575
Voltage 50/60Hz 1phase [V]	-
Average power consumption [kW]	2.5

### Integrated services

Integrated signals on upper arm In/Out	8/8
Integrated air supply	2

### Environment

Acoustic noise level [dB]	< 70
Ambient temperature [° C]	0-45

### Protection

Body standard/optional	IP54/IP56
Wrist & J3 arm standard/optional	IP67

● standard ○ on request - not available ( ) with hardware and/or software option

\*Based on ISO9283