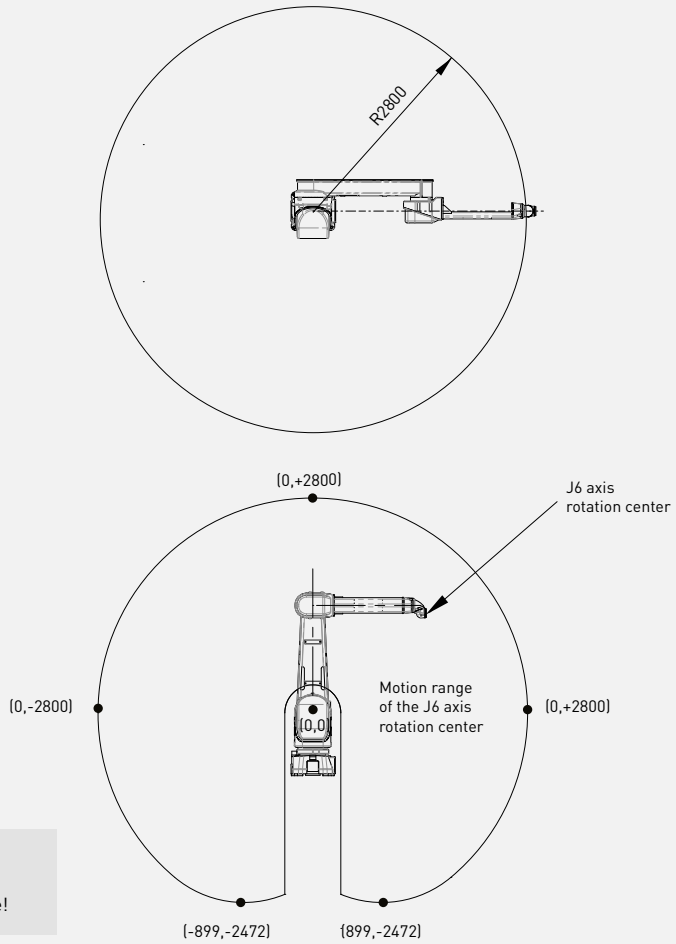
P-250*i*B/15 (Hollow wrist)

Max. load capacity at wrist: **15 kg**

Max. reach: **2800 mm**

Controlled axes	Repeatability (mm)	Mechanical weight (kg)	Motion range (°)						Maximum speed (°/s)						J4 Moment/ Inertia (Nm/kgm²)	J5 Moment/ Inertia (Nm/kgm²)	J6 Moment/ Inertia (Nm/kgm²)
			J1	J2	J3	J4	J5	J6	J1	J2	J3	J4	J5	J6			
6	± 0.2	530	360	280	330	1080	1080	1080	160	160	160	375	430	545	65.4/2.999	55.3/2.158	7.4/0.073

Working range



Motion range may be restricted according to the mounting angle!

Robot	**P-250*i*B/15**
Robot footprint [mm]	560 x 500
Mounting position Floor	●
Mounting position Upside down	●
Mounting position Angle	●
Controller	**R30*i*B**
Open air cabinet	-
Mate cabinet	-
A-cabinet	●
B-cabinet	-
*i*Pendant Touch	●
Electrical connections	
Voltage 50/60Hz 3phase [V]	200-575
Voltage 50/60Hz 1phase [V]	-
Average power consumption [kW]	3.5
Integrated services	
Integrated signals on upper arm In/Out	-
Integrated air supply	-
Environment	
Acoustic noise level [dB]	< 86.4
Ambient temperature [° C]	0-45
Protection	
Body standard/optional	*5
Wrist & J3 arm standard/optional	*5

*5) ATEX certified Cat. II Group 2G and 2D

● standard o on request - not available ( ) with hardware and/or software option

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